



Trajectory Based Forwarding and Its Applications¹

Dragoş Niculescu and Badri Nath
{dnicules,badri}@cs.rutgers.edu

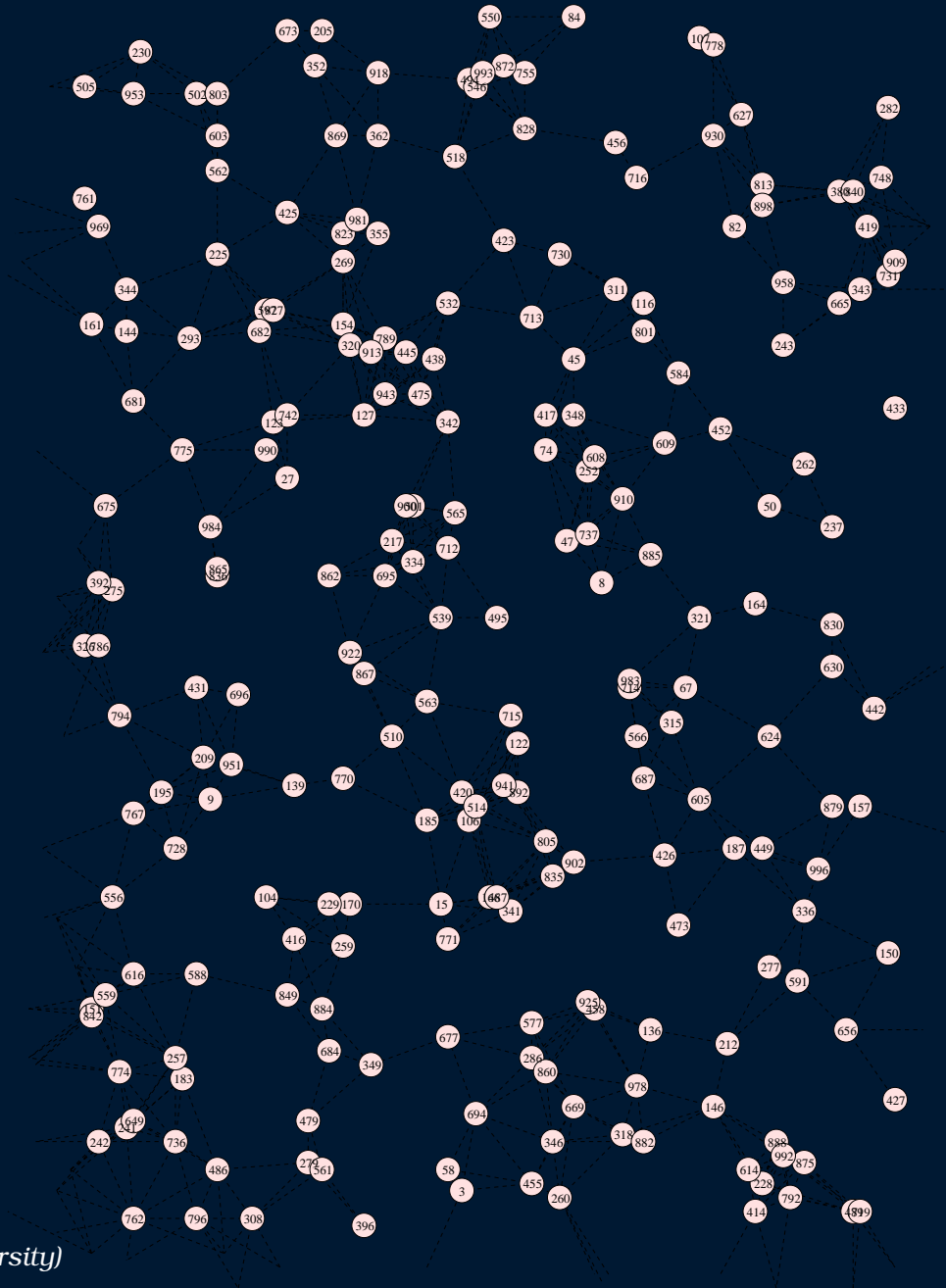
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¹funded in part by NSF and DARPA

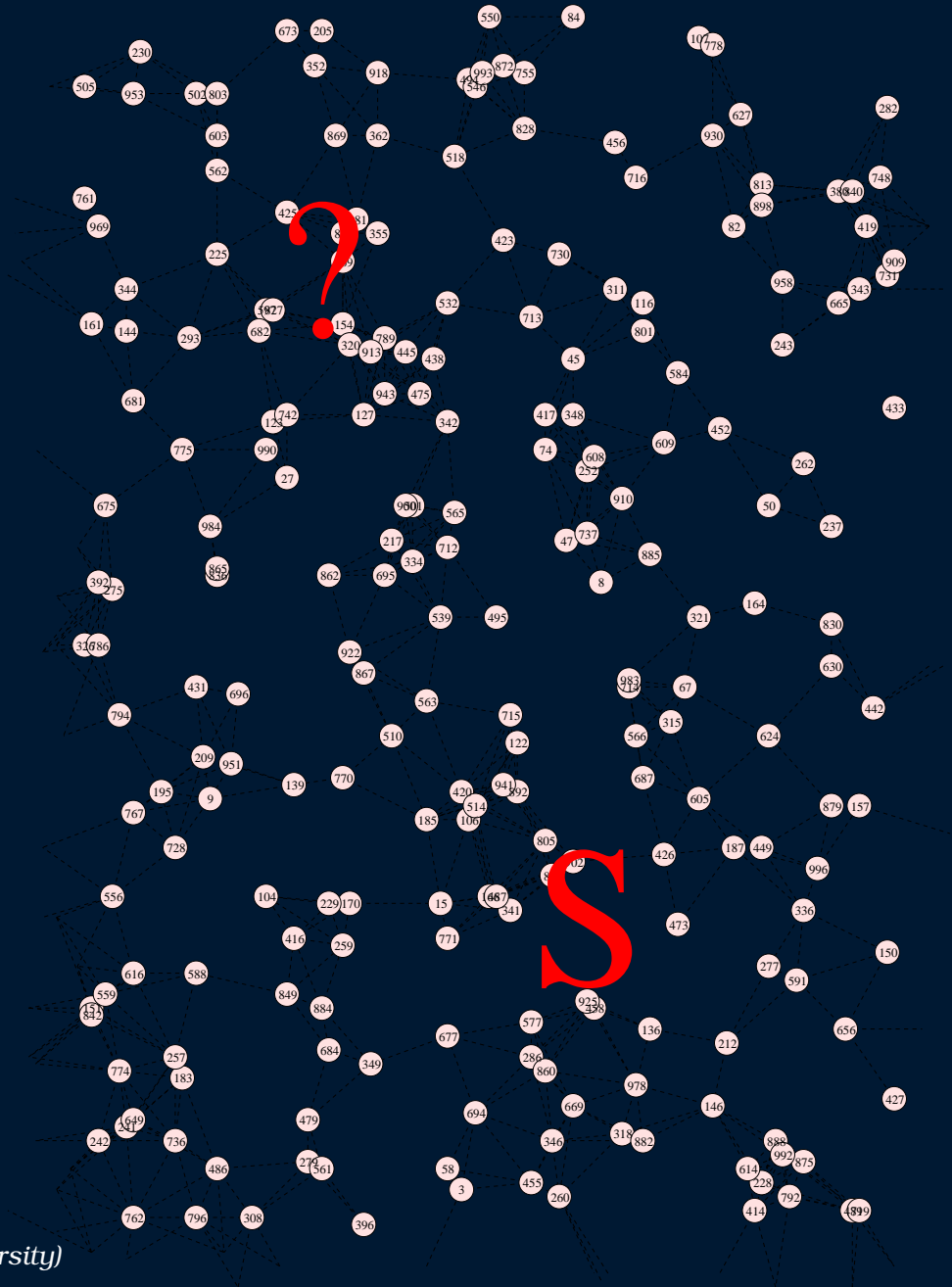
problems in ad hoc networks

2

- **discover**
- **route**
 - **multipath**
 - **mobile source**
 - **multicast**
- **scalability issues**
 - **routing tables**
 - **flooding**

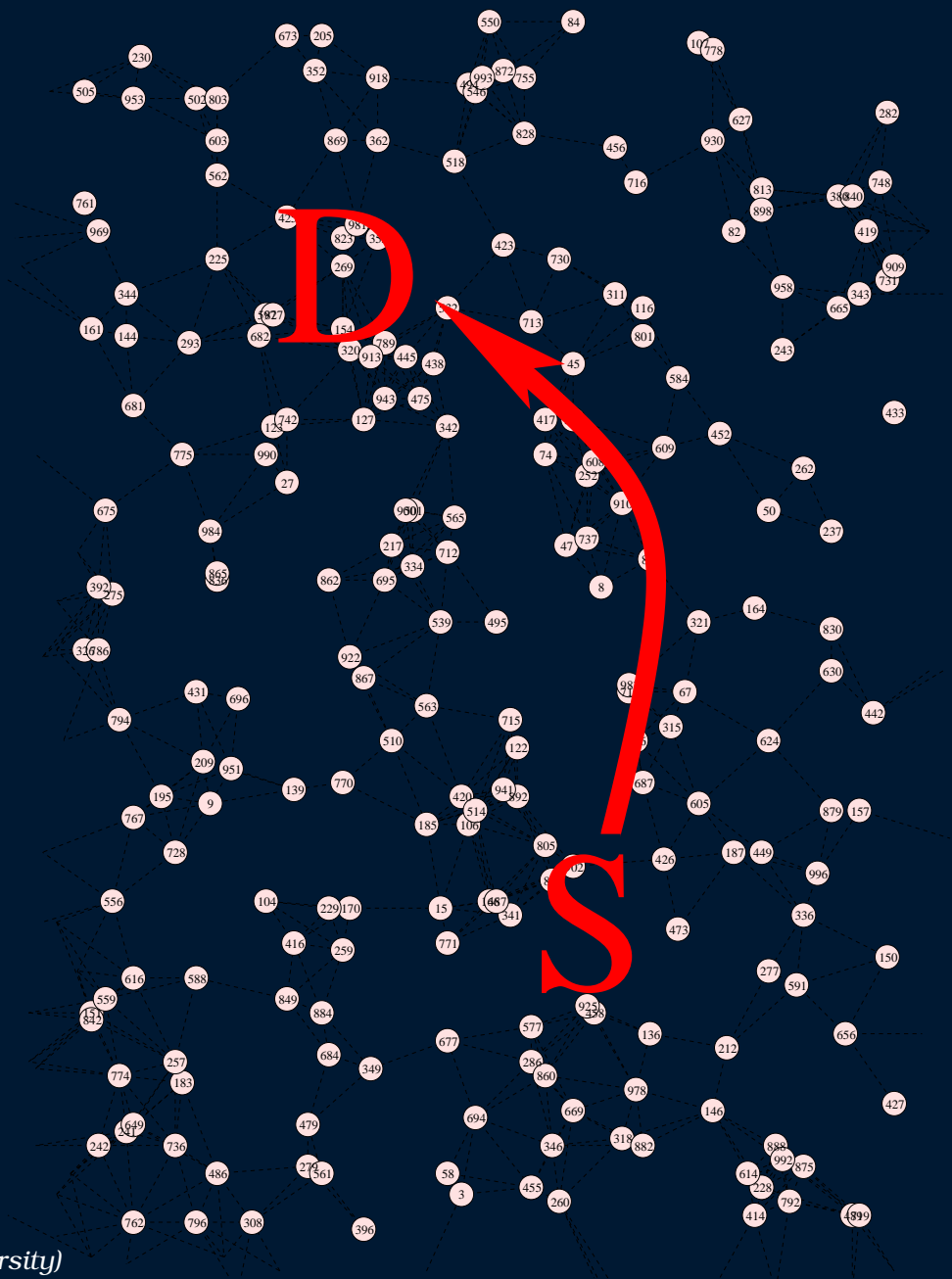


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- route
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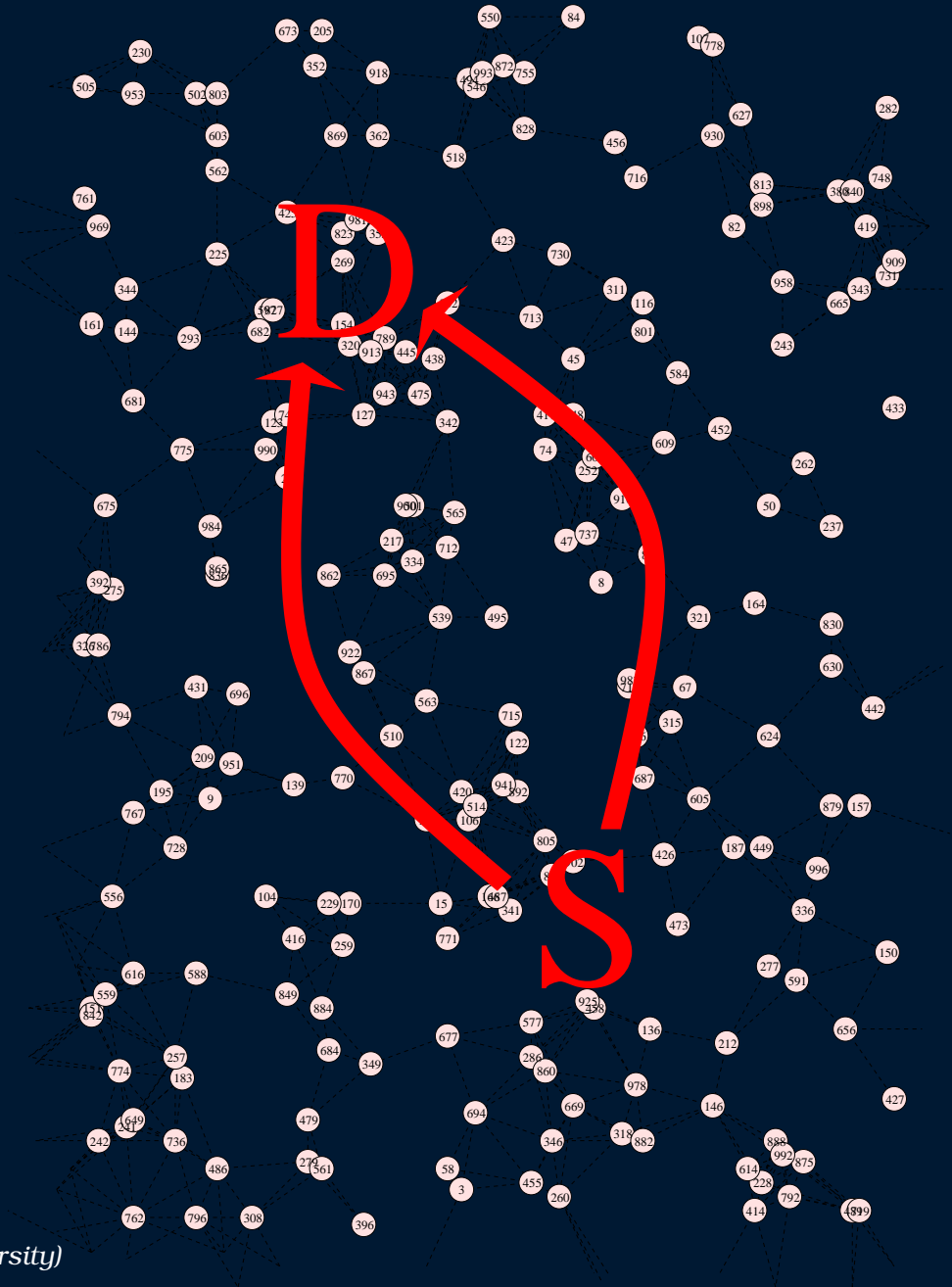


problems in ad hoc networks

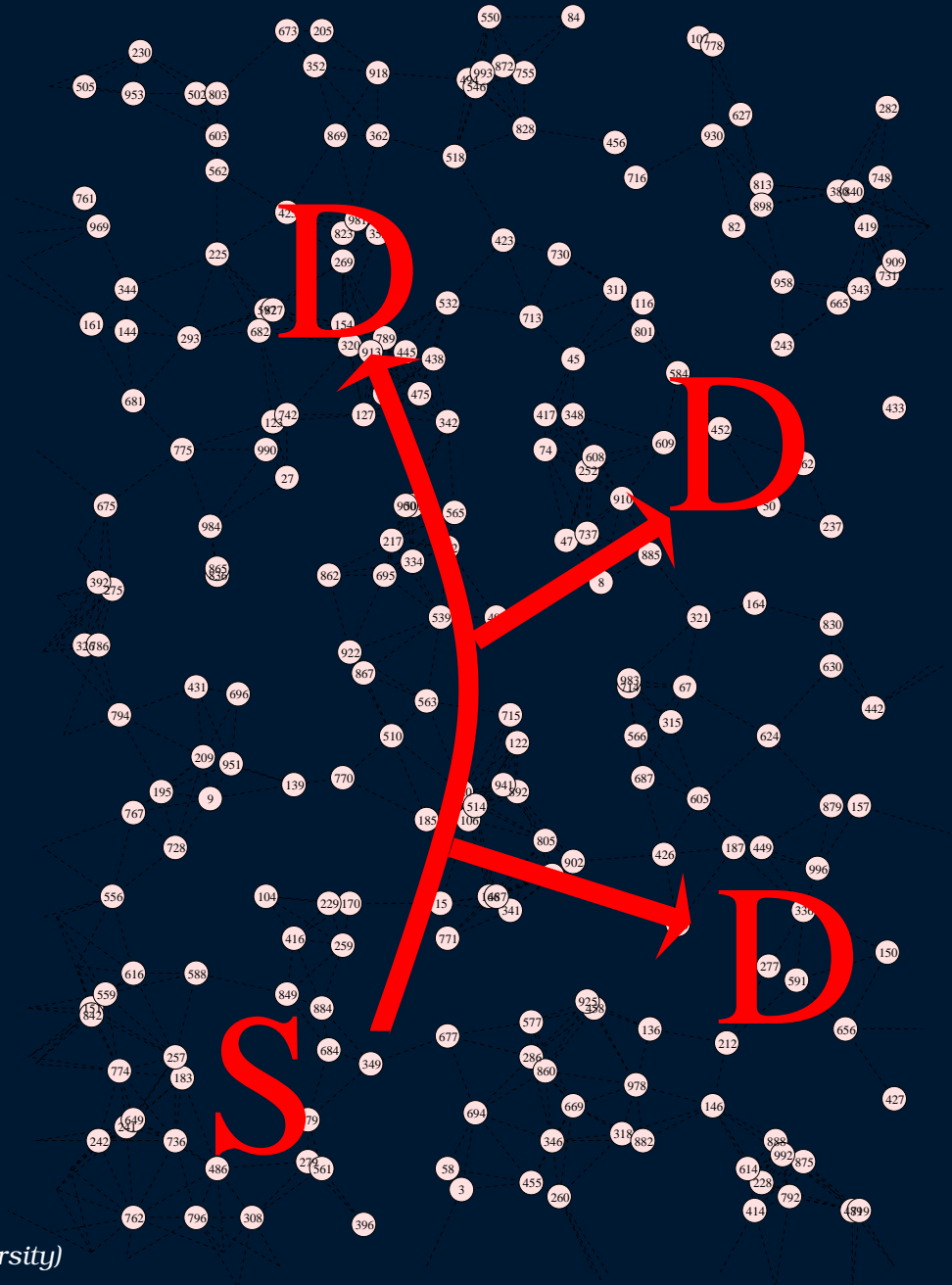
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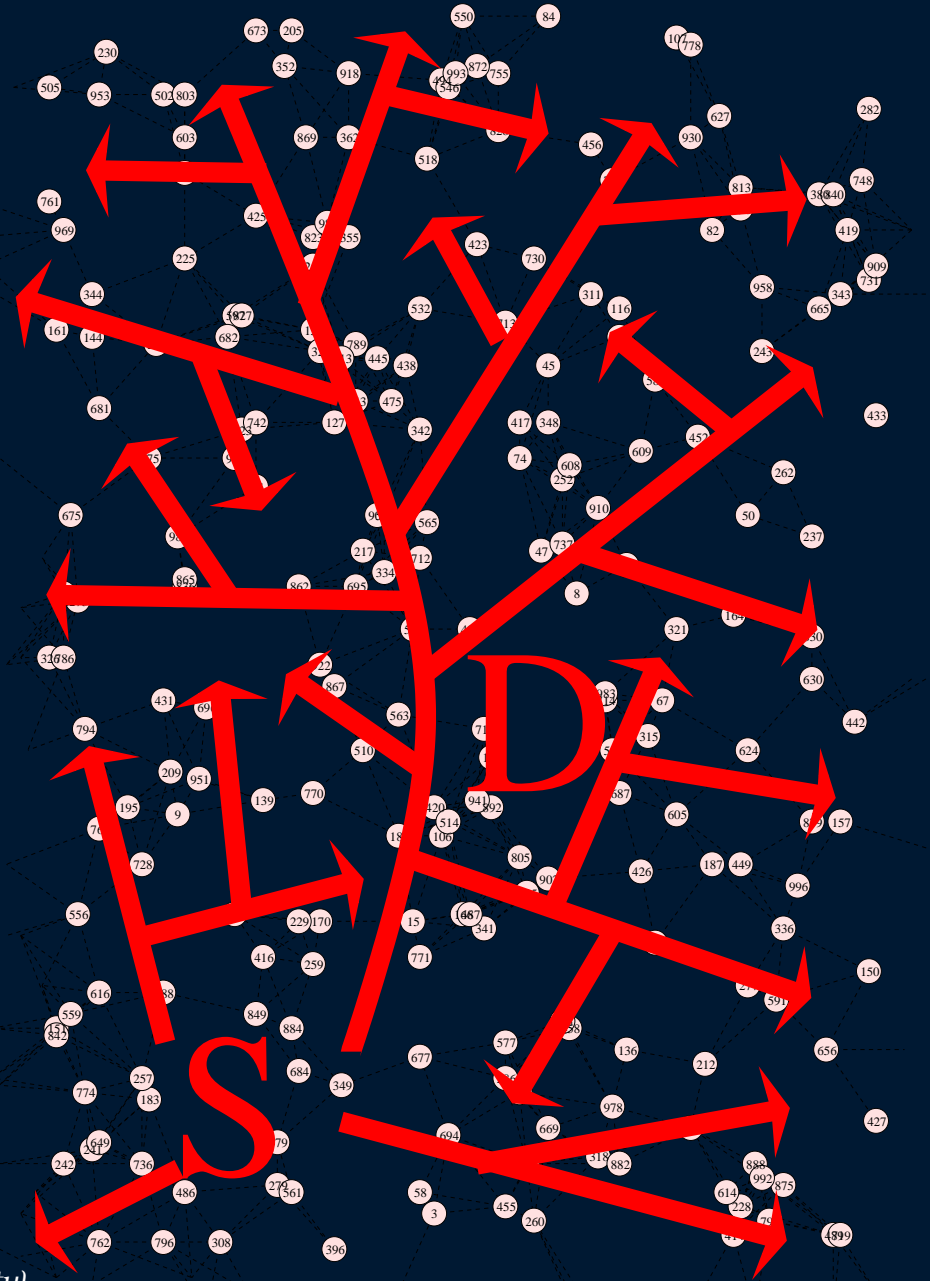
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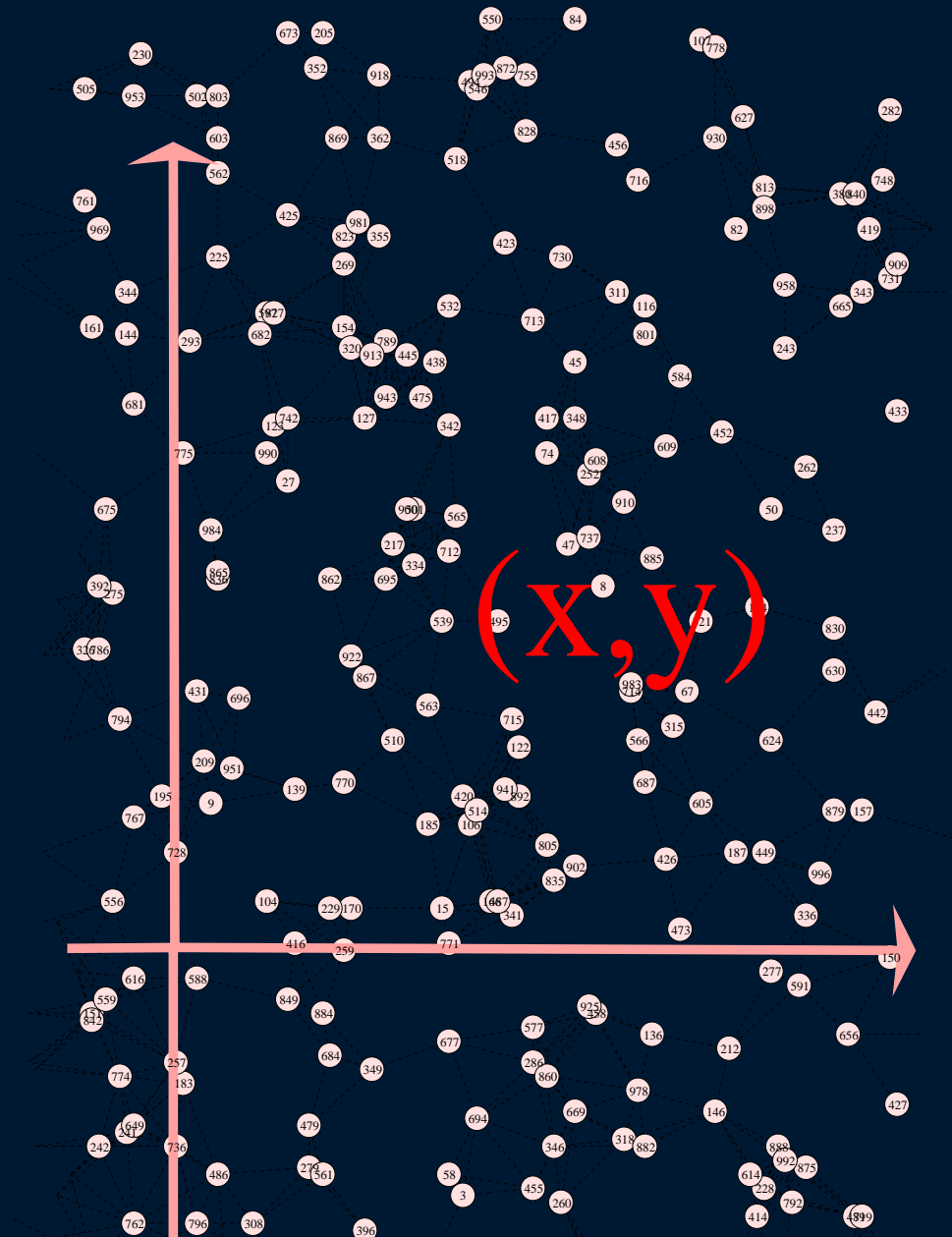
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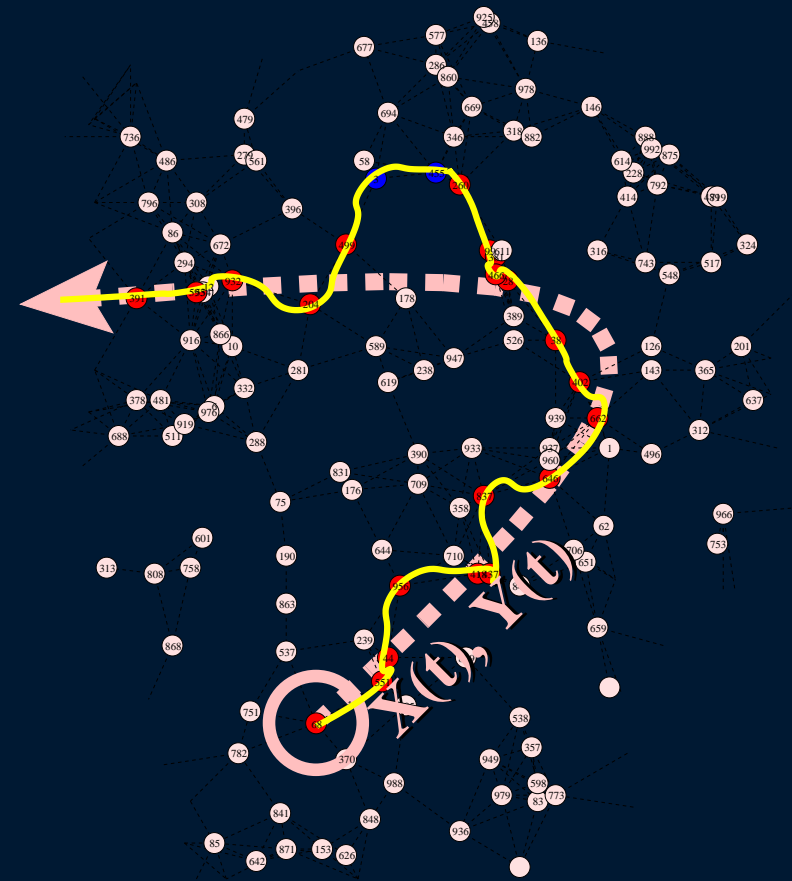
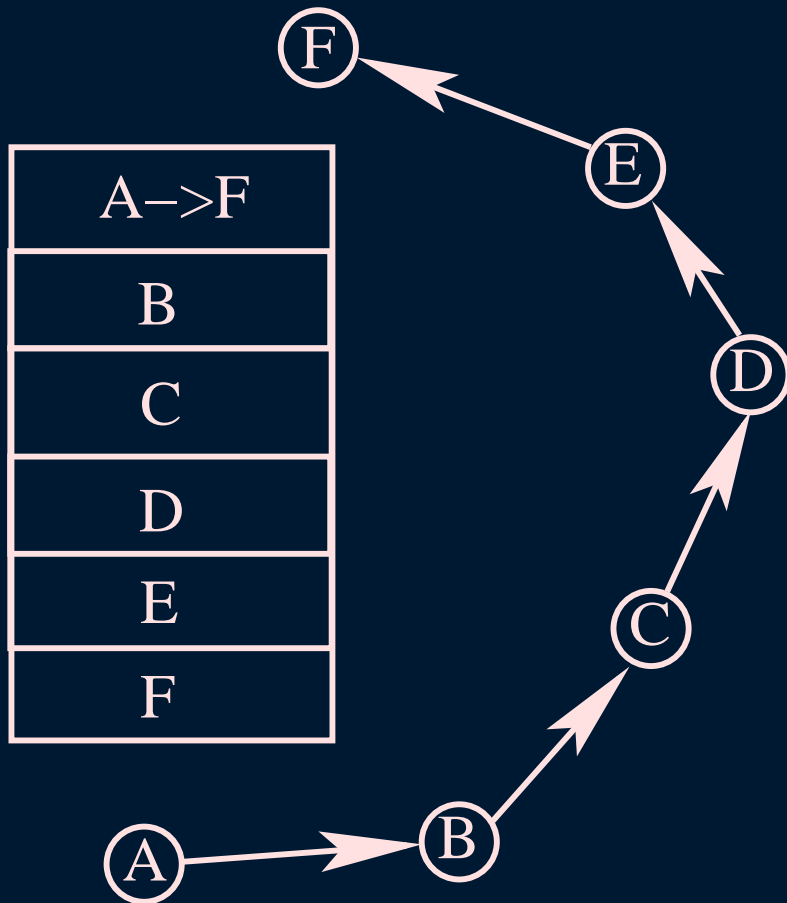
- **discover**
- **route**
 - **multipath**
 - **mobile source**
 - **multicast**
- **scalability issues**
 - **routing tables**
 - **flooding**
 - **mobility**



- discover
- route
 - multipath
 - mobile source
 - multicast
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 - flooding
 - mobility



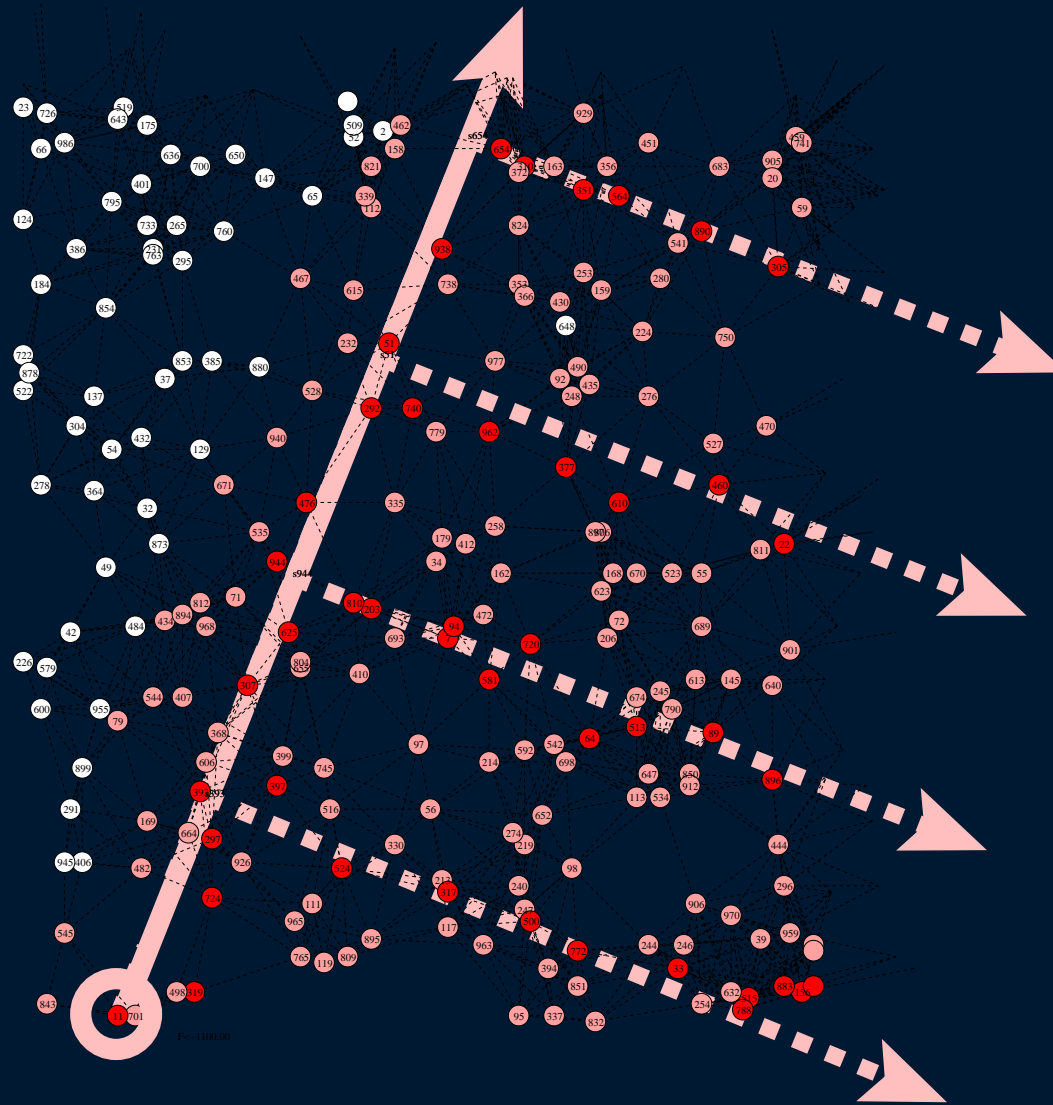
- **broadcasting** → **classical, probabilistic**[Haas00]
- **discovery** → **flooding, GLS**[Li00], **DREAM**[Basagni98]
- **routing**
 1. **node centric** → **DSDV**[Perkins94], **DSR**[Johnson96], **AODV**[Perkins97], **ZRP**[Haas99]
 - **flooding**
 - **routing tables**
 - **multipath?**
 2. **data centric** → **diffusion**[Intanago00]
 3. **position centric**
 - **MFR**[Kleinrock76], **Cartesian**[Finn87],
 - **LAR**[Vaidya98], **DREAM**[Basagni98]
 - **Georoute**[Navas98]



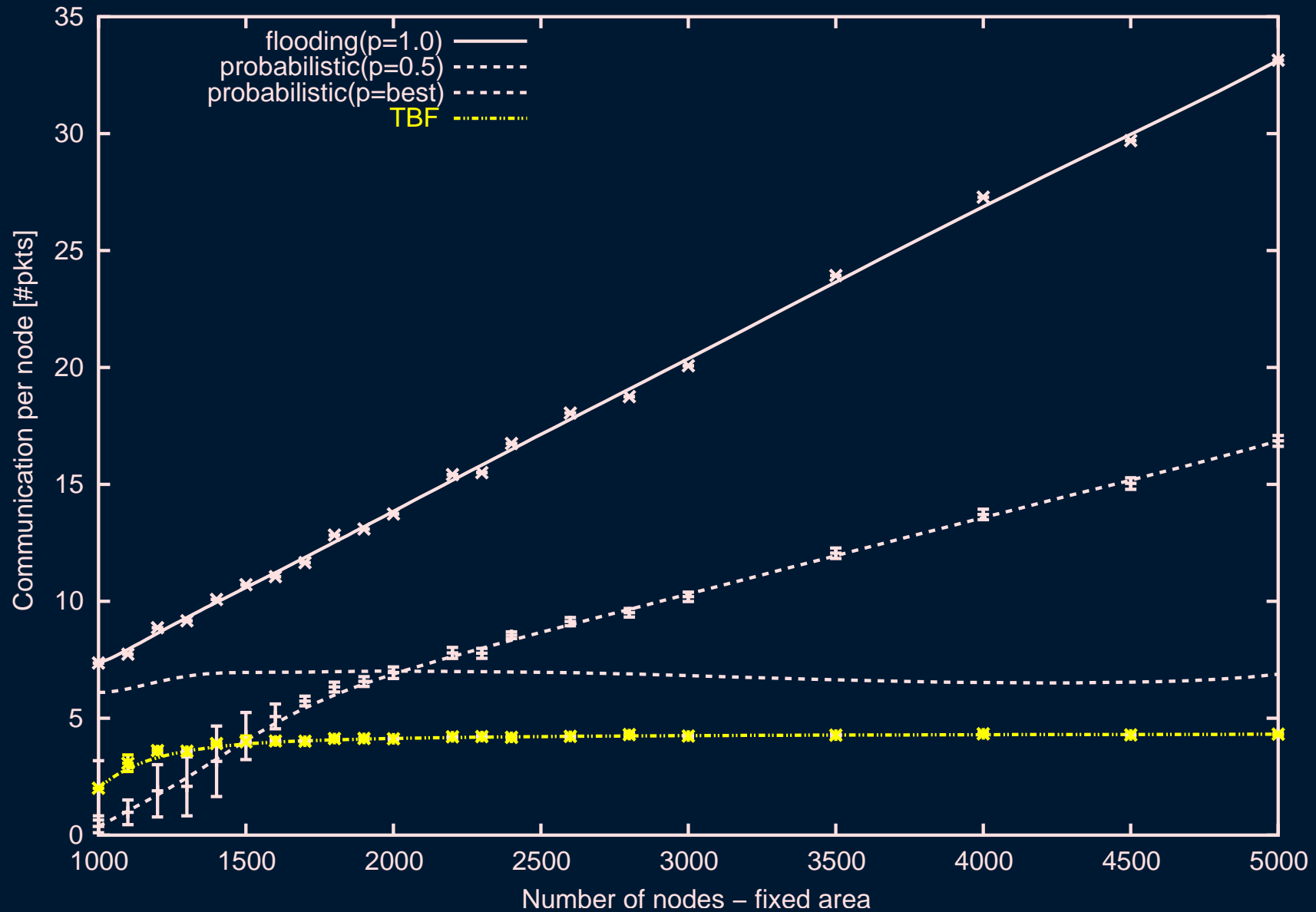
- discrete paths
- overhead \simeq path length
- mobility \rightarrow updates
- **continuous paths**
- fixed overhead
- no maintenance

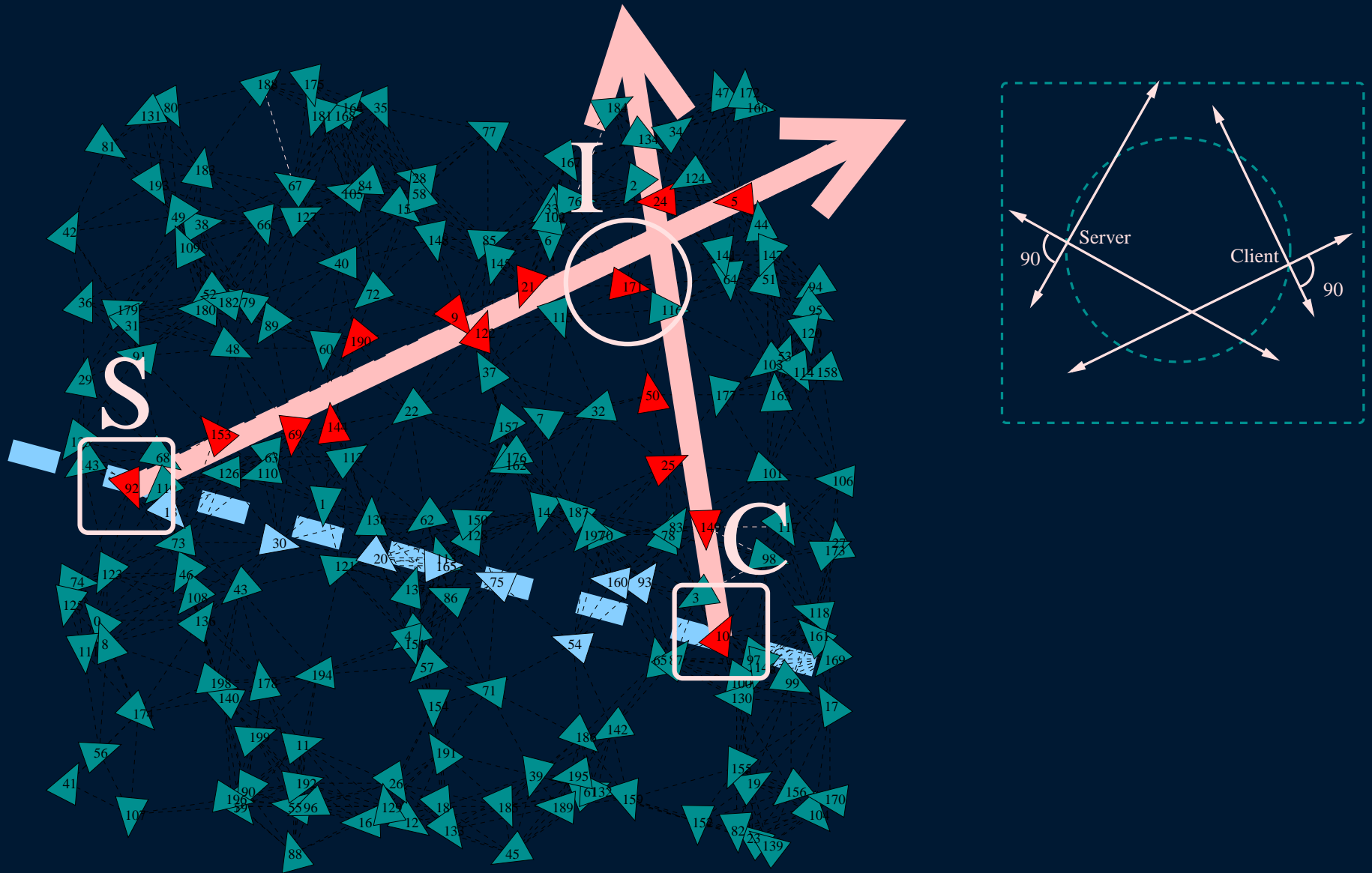
1. **cheap path diversity**
2. **decouples path name from actual path**
 - no routing tables
 - fixed packet overhead
 - scalable for **LARGE/DENSE** networks
3. **common framework**
 - routing: unicast, multicast, multipath
 - discovery
 - broadcasting
4. **simple to implement**

TBF based broadcasting



TBF based broadcasting





1. mobile network, static destination

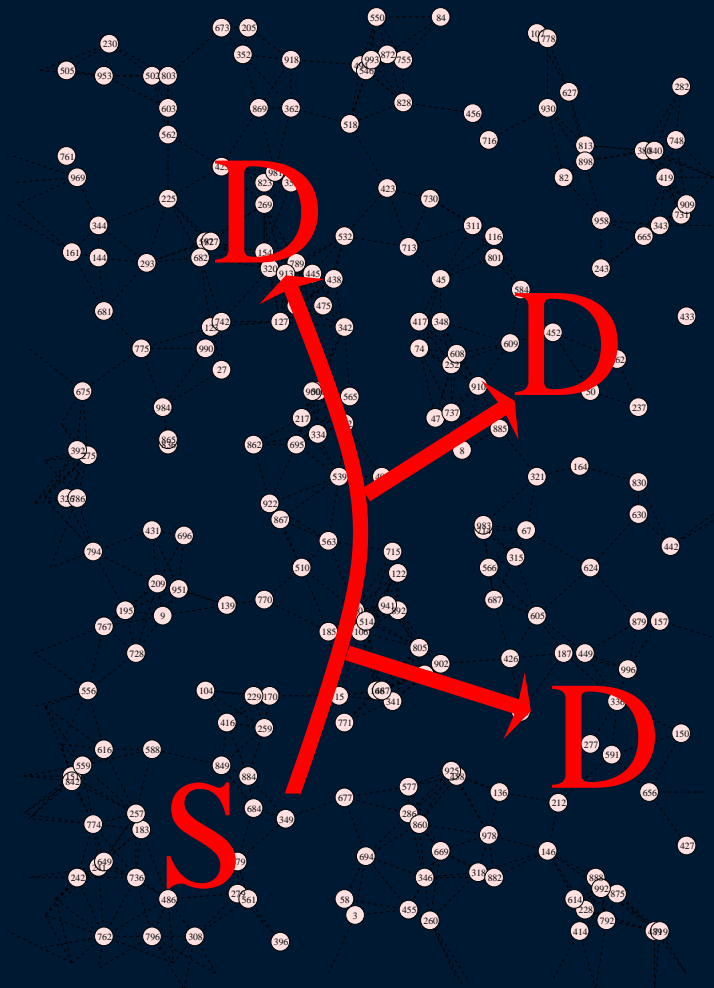
- (decouples path name from the actual path)

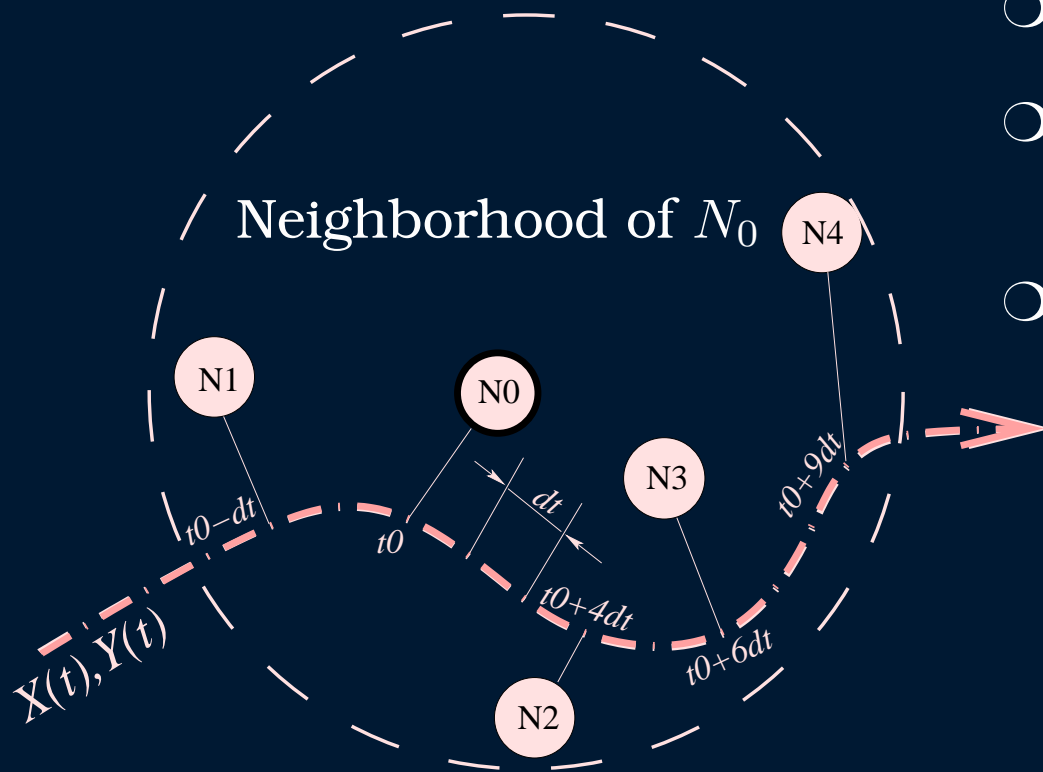
2. multipath, load balancing

- (path diversity)

3. quick and dirty

- multi-resolution discovery
- point to multipoint

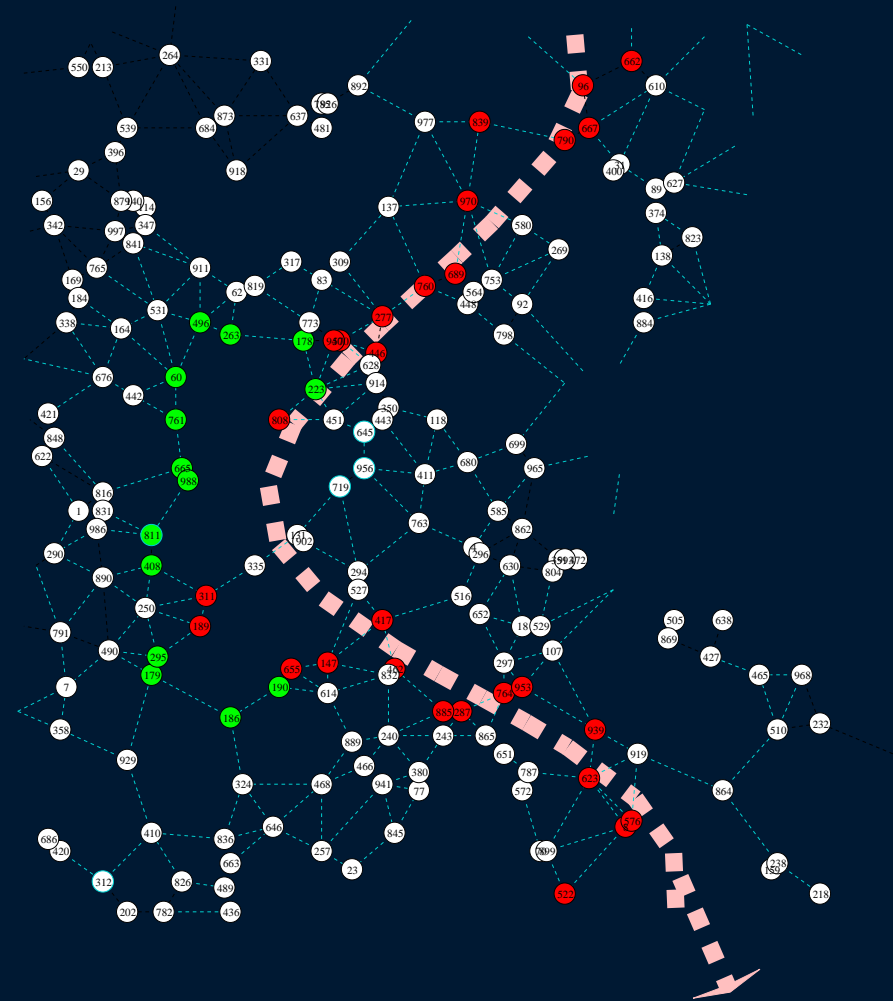




- **node N_0 :**
- **receives $X(t), Y(t)$ - encoded curve**
- **chooses a next hop**
 - **closest to trajectory (N_2)**
 - **maximum advancement (N_4)**
 - **most battery left**

sparse networks

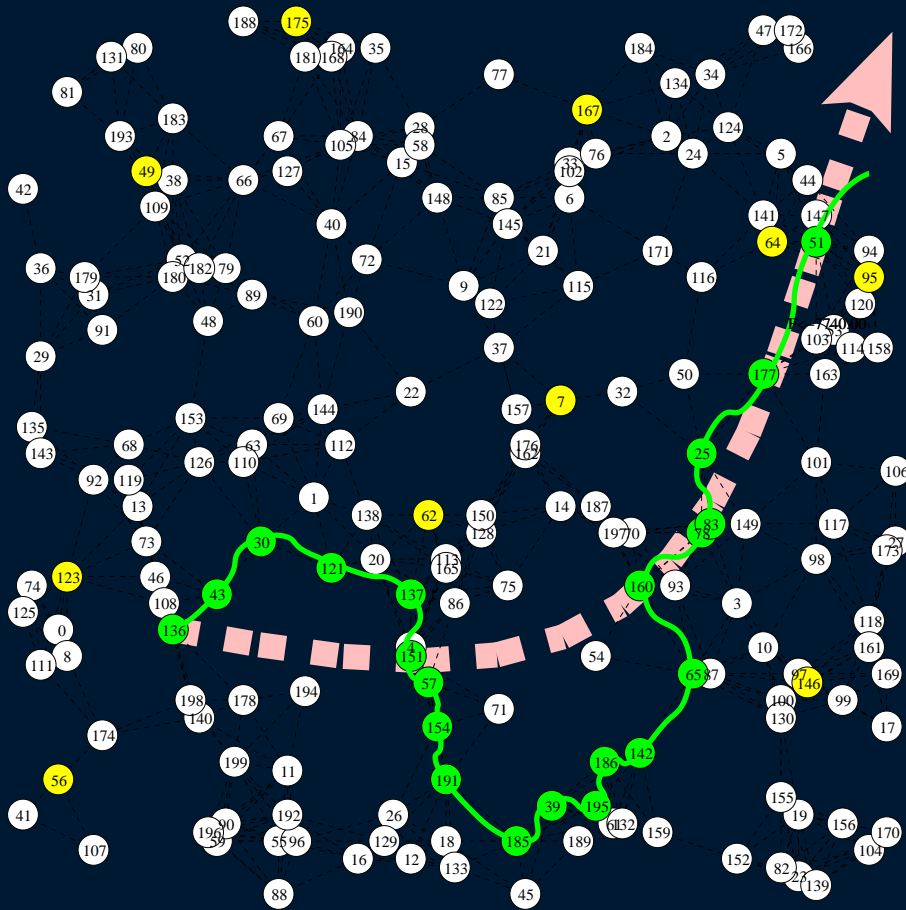
- Greedy Face Greedy [BoseMorin99][Karp00]
- planarized graph
- right hand rule
- TBF: hard to guarantee delivery



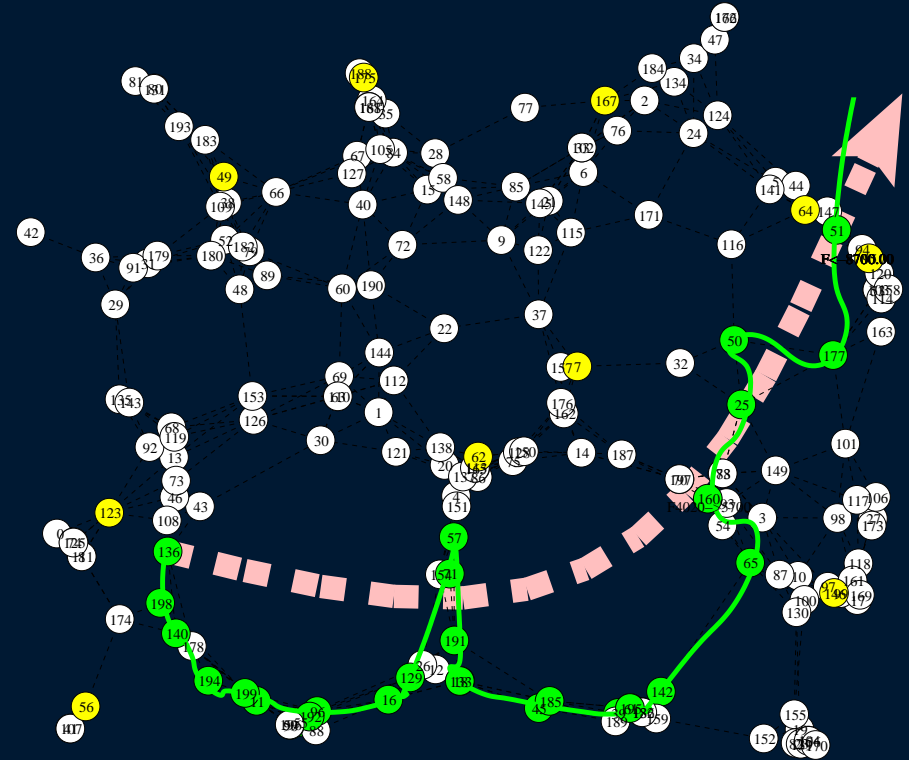
no positioning

- **assume other capabilities**
 - **AoA, ranging, compass, accelerometer**
- **use localized schemes**
 - **some landmarks: APS, AhLOS, SPA**
 - **no landmarks:**
LPS (Local Positioning System)
- **produce imprecise positions**

use of imprecise positions

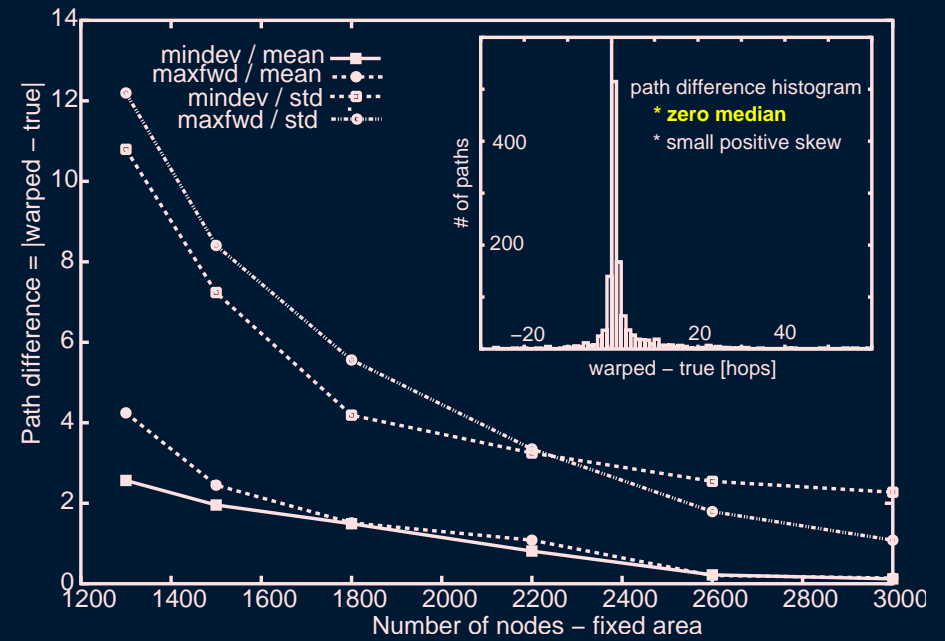
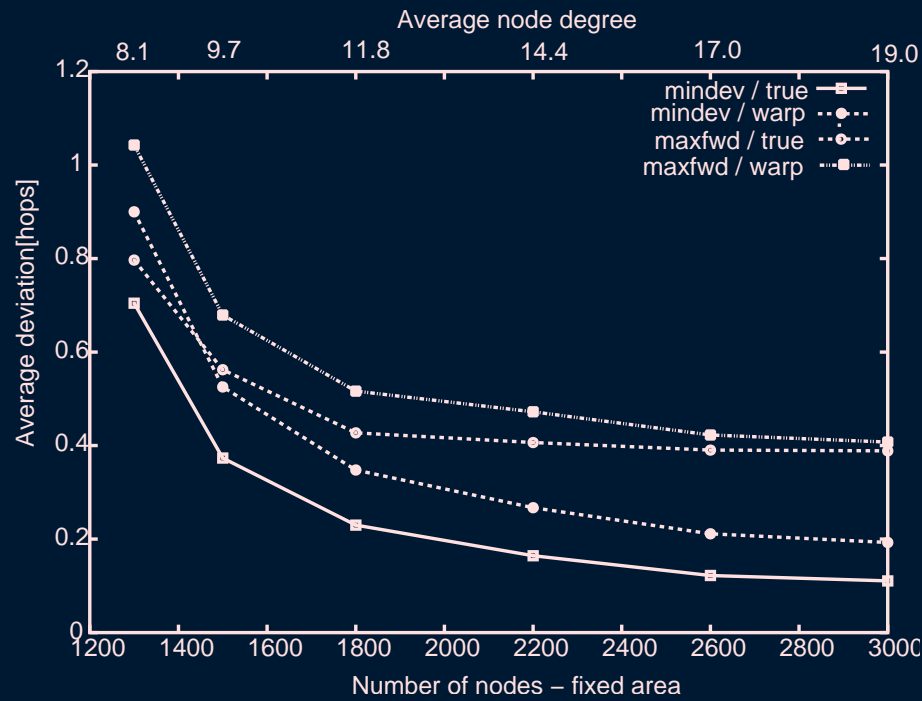


true space

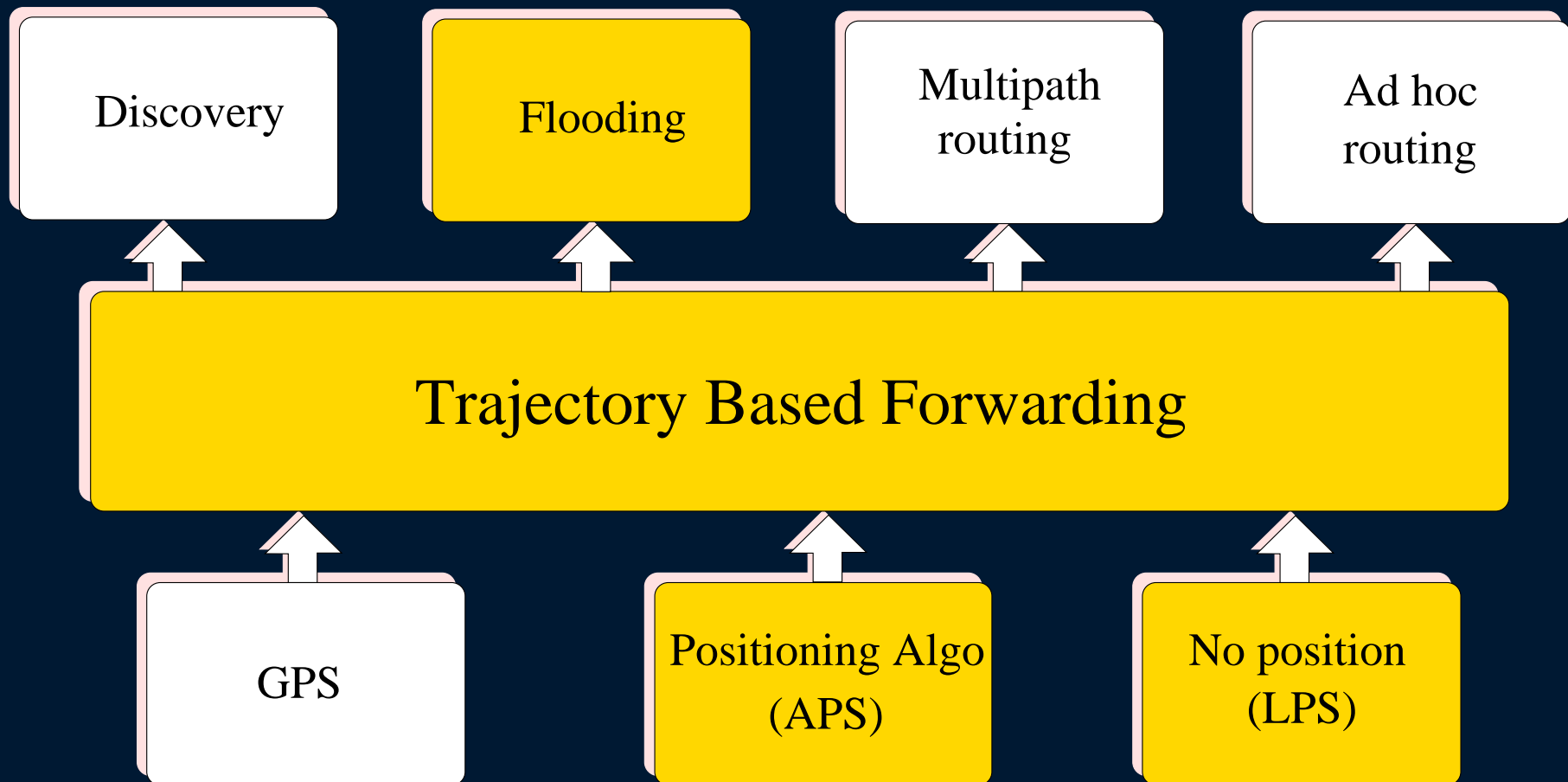


warped space

- landmark node
- forwarding node
- ➔ ideal trajectory
- achieved trajectory



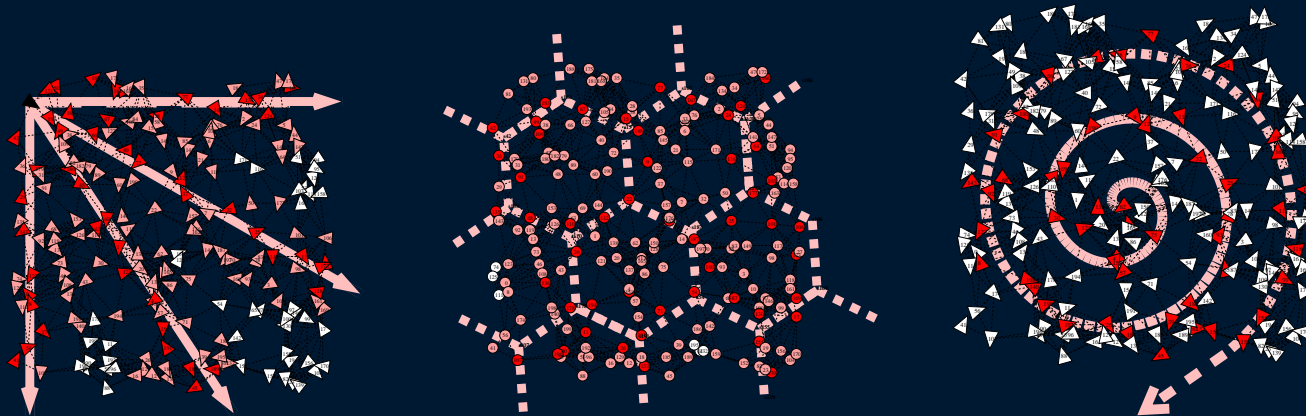
paths = 15..25 hops; degrees = 8..20; 200 random pairs;



- **trajectory encoding**
 - **wavelets, polynomial**
- **determination:**
 - **mapping service**
- **modification and patching**
- **imprecise information**
- **multicast trees**
- **load balancing**
- **performance evaluation: mobility, TCP,...**

- decouples path naming from the actual path
- **provides cheap path diversity**
- **saves energy**
- **provides common framework for:**
 - **routing: unicast, multicast, multipath**
 - **flooding: stateless, stateful, multiresolution**
 - **discovery**
- **needs positioning** → wide range of assumptions

<http://www.cs.rutgers.edu/~dnicules/research/>



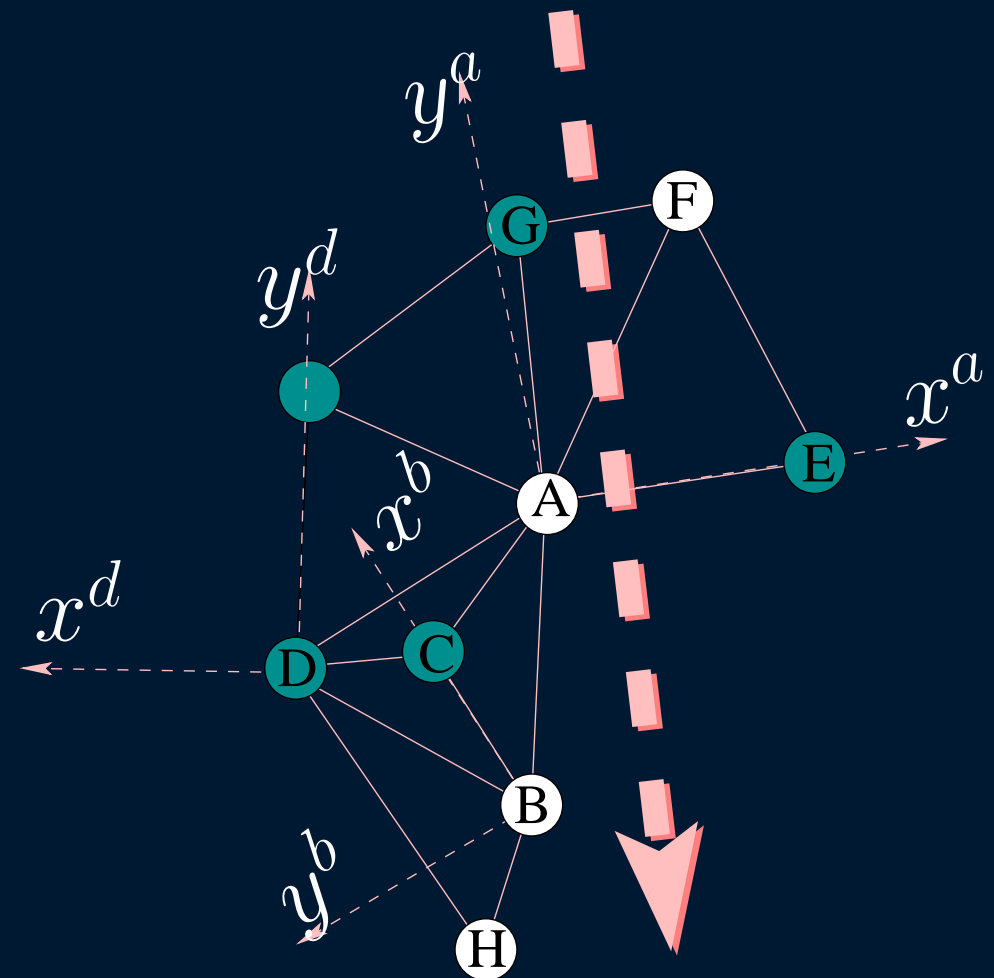
- **problems**
- **previous work**
- **TBF**
- **why is it good?**
- **broadcasting**
- **discovery**
- **when is it best?**
- **how it forwards**
- **adverse conditions**
 - **imprecise positions**
- **overhead**
- **LPS**
- **vision**
- **future work**

Localized Positioning System

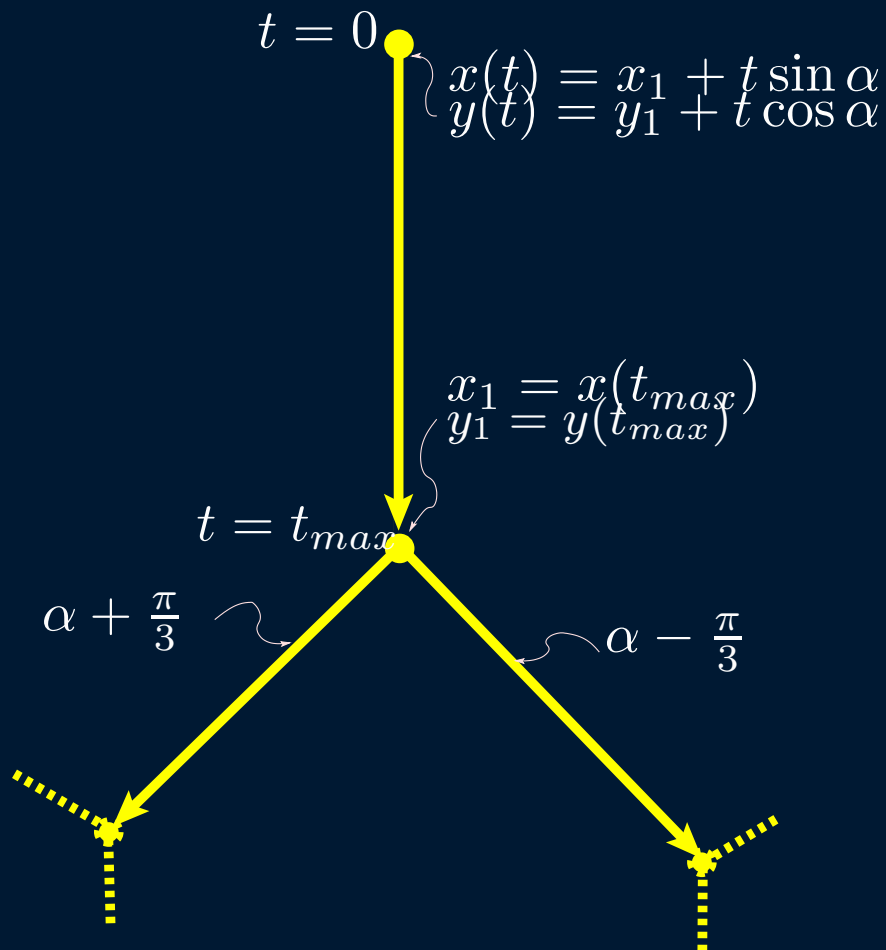


- **no GPS in the network**
- **need certain capabilities**
 - ranging
 - angle of arrival
 - compass, accelerometer
- **positioning**
 - **only for nodes on the trajectory**
 - **in the coordinate system of the source**
- **forwarding, not routing**

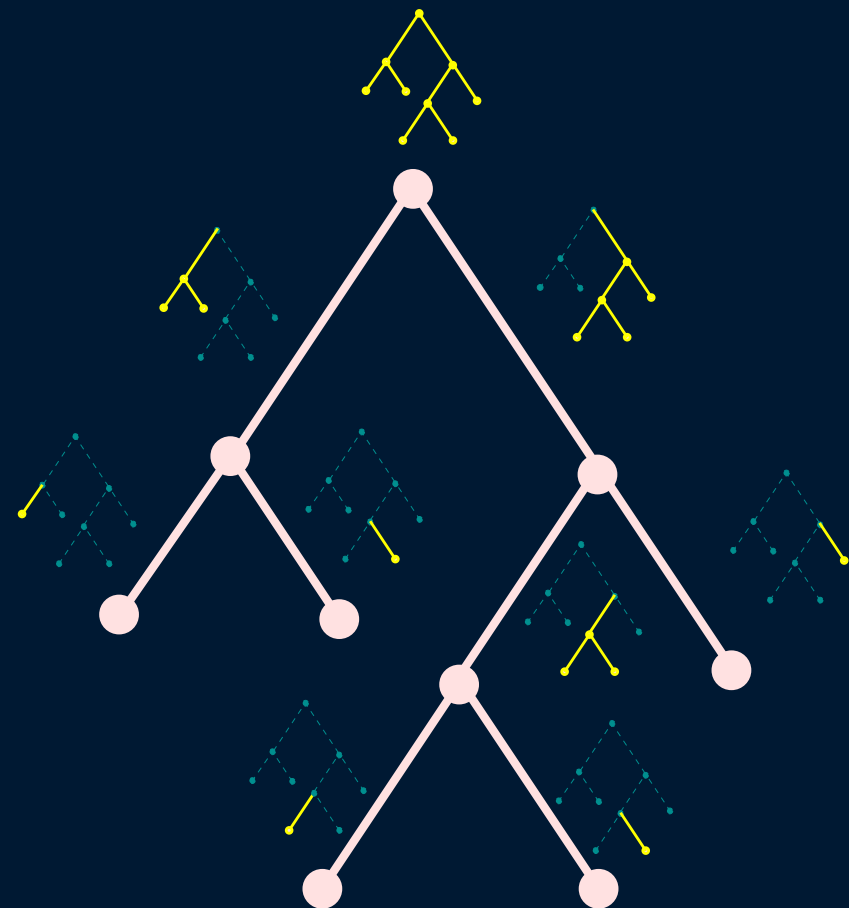
- nodes builds local coordinate systems
- trajectory is evaluated in the original coordinate system
- **registration:** align coordinate systems
- **optimization:** preregister with all neighbors



REGULAR TREE



ARBITRARY TREE



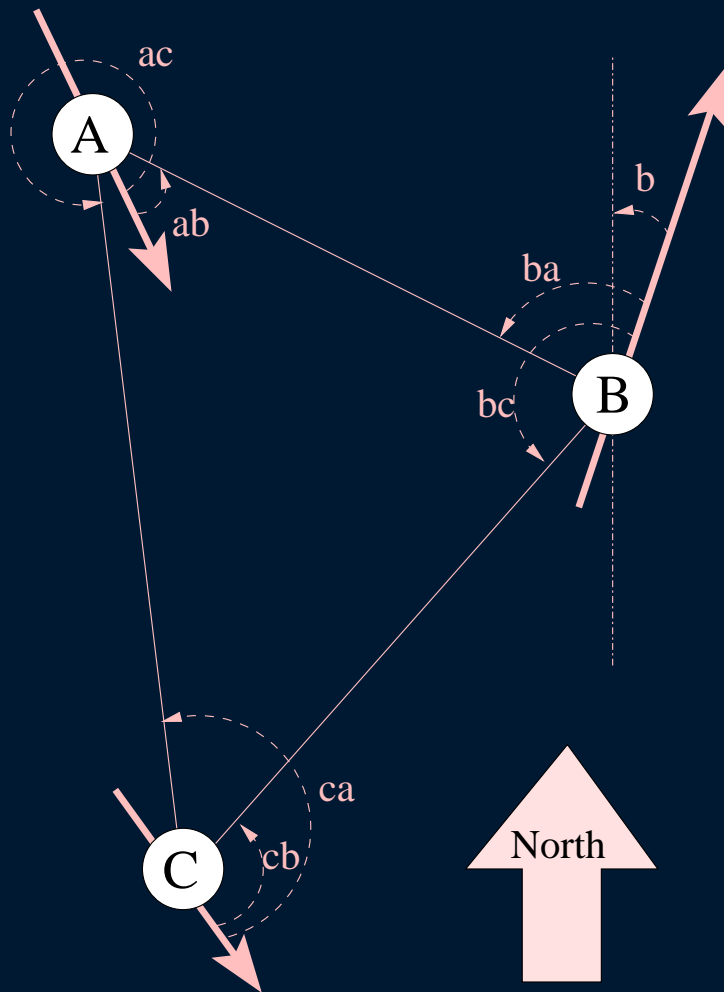
packet overhead

- **independent on**
 - **density**
 - **path length**
- **depends on representation**
- **polish notation (RPN)**
 - **best flexibility**
- **function tables**
 - **parameters in packet**
 - **most compact**

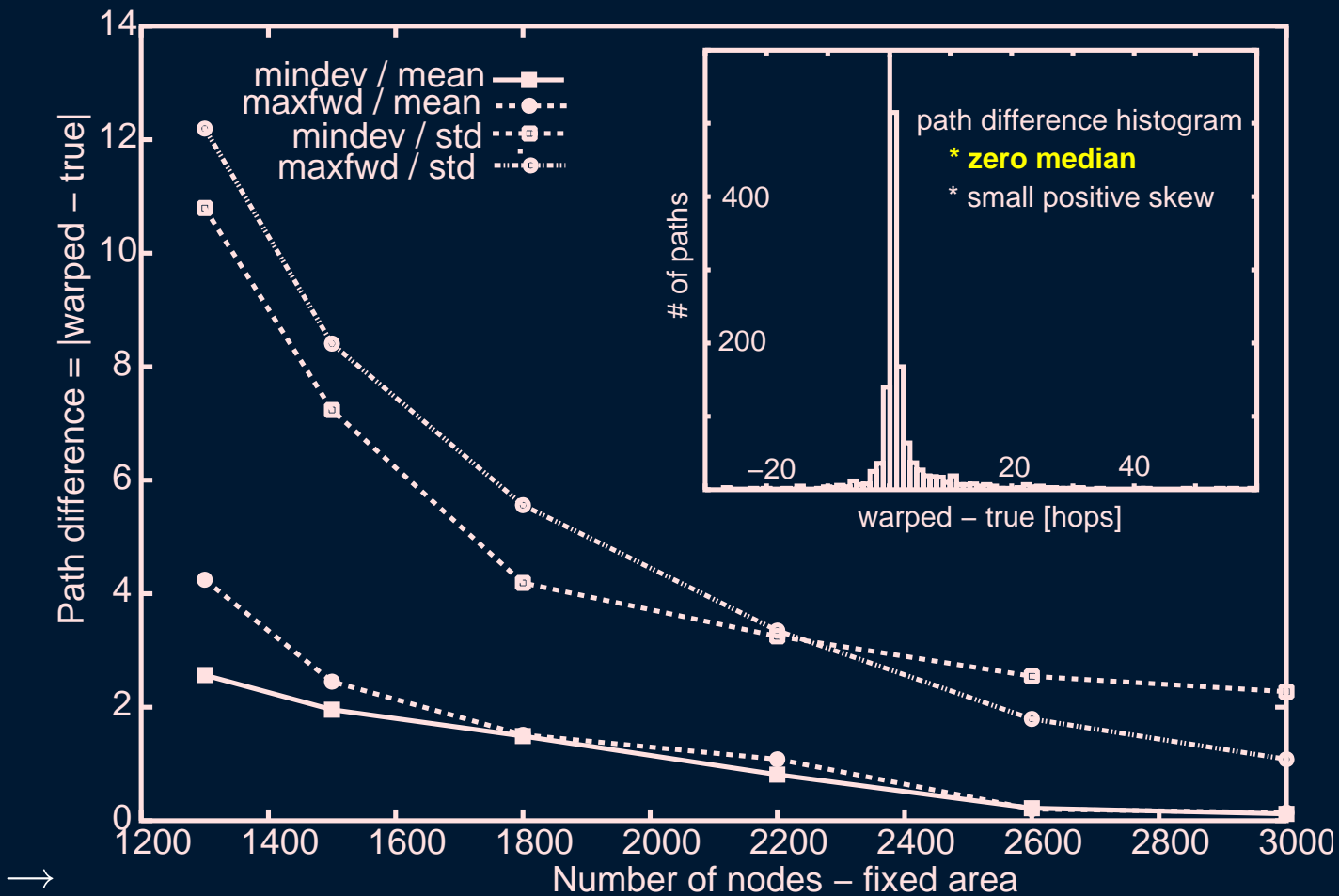
CPU overhead

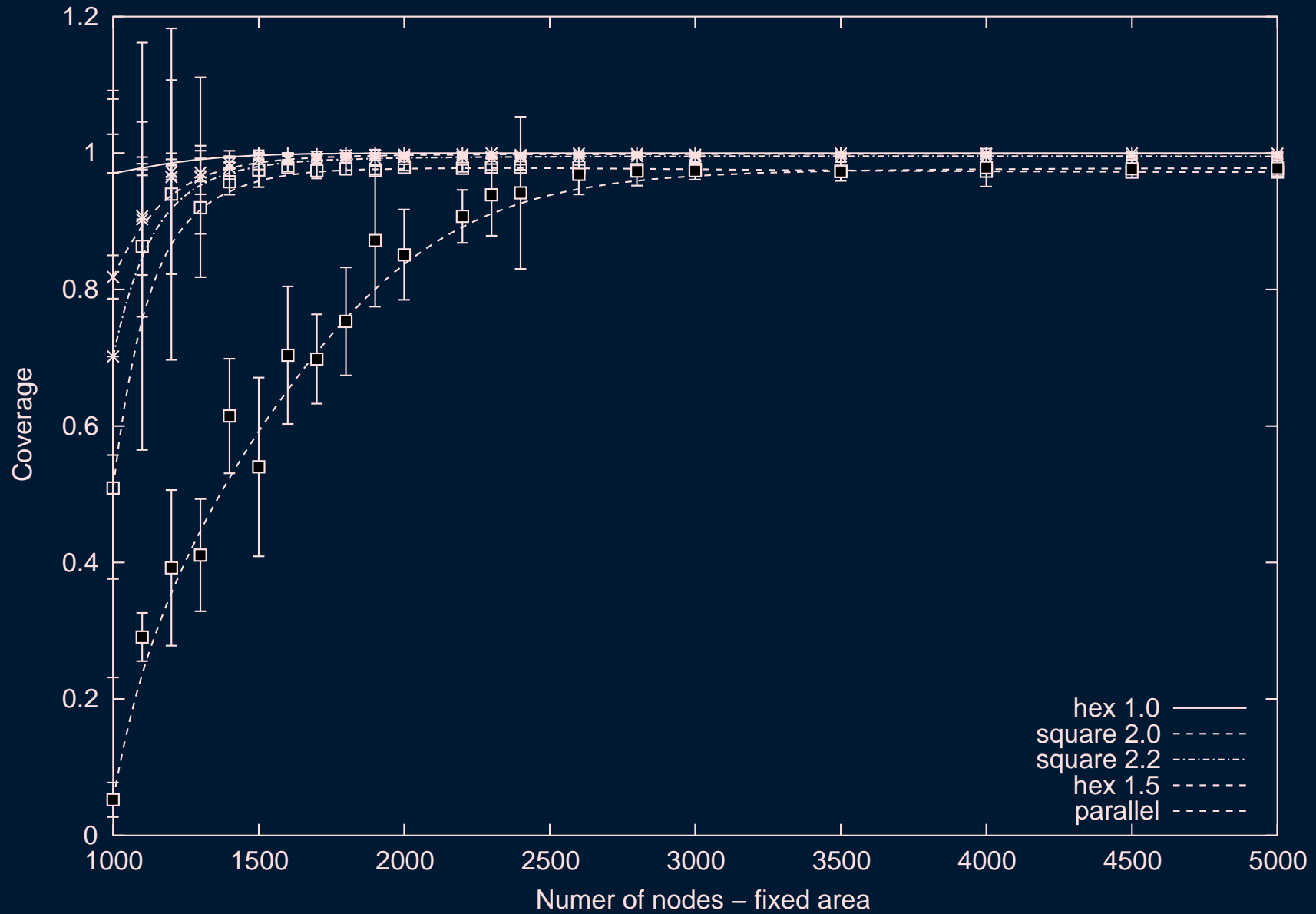
- **dependent on**
 - **density**
 - **path length**
- **curve discretization**
- **positioning**

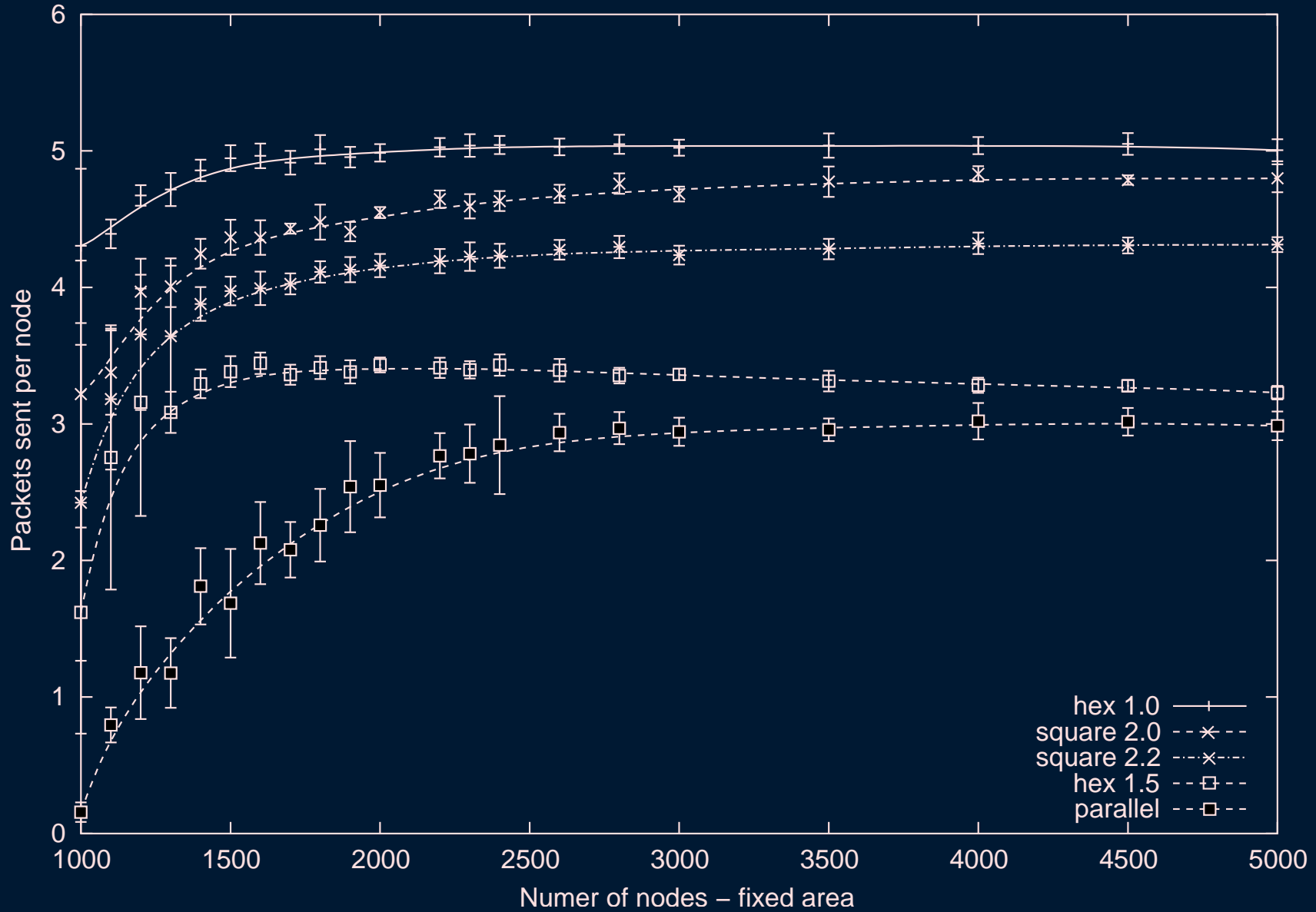
node capabilities

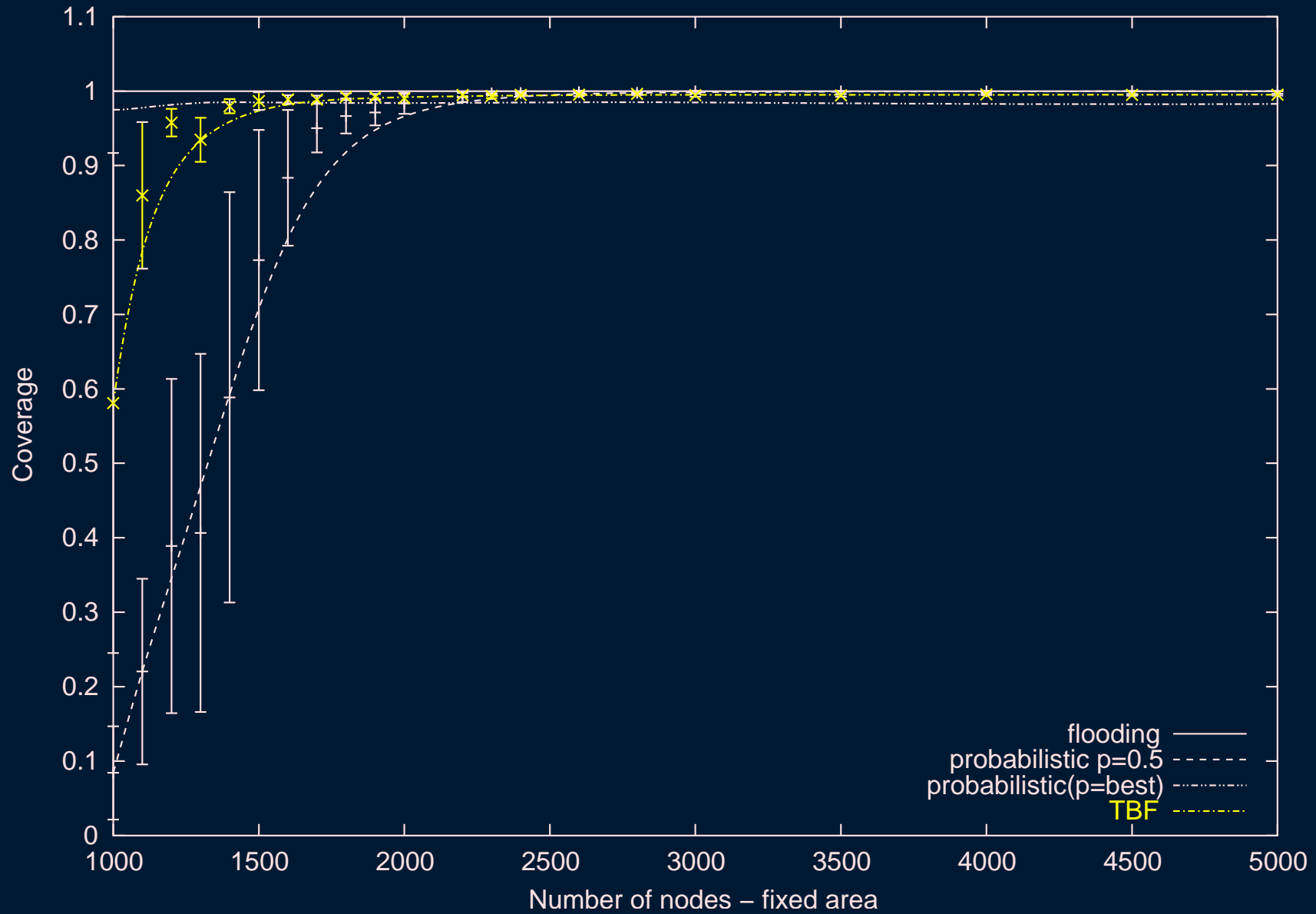


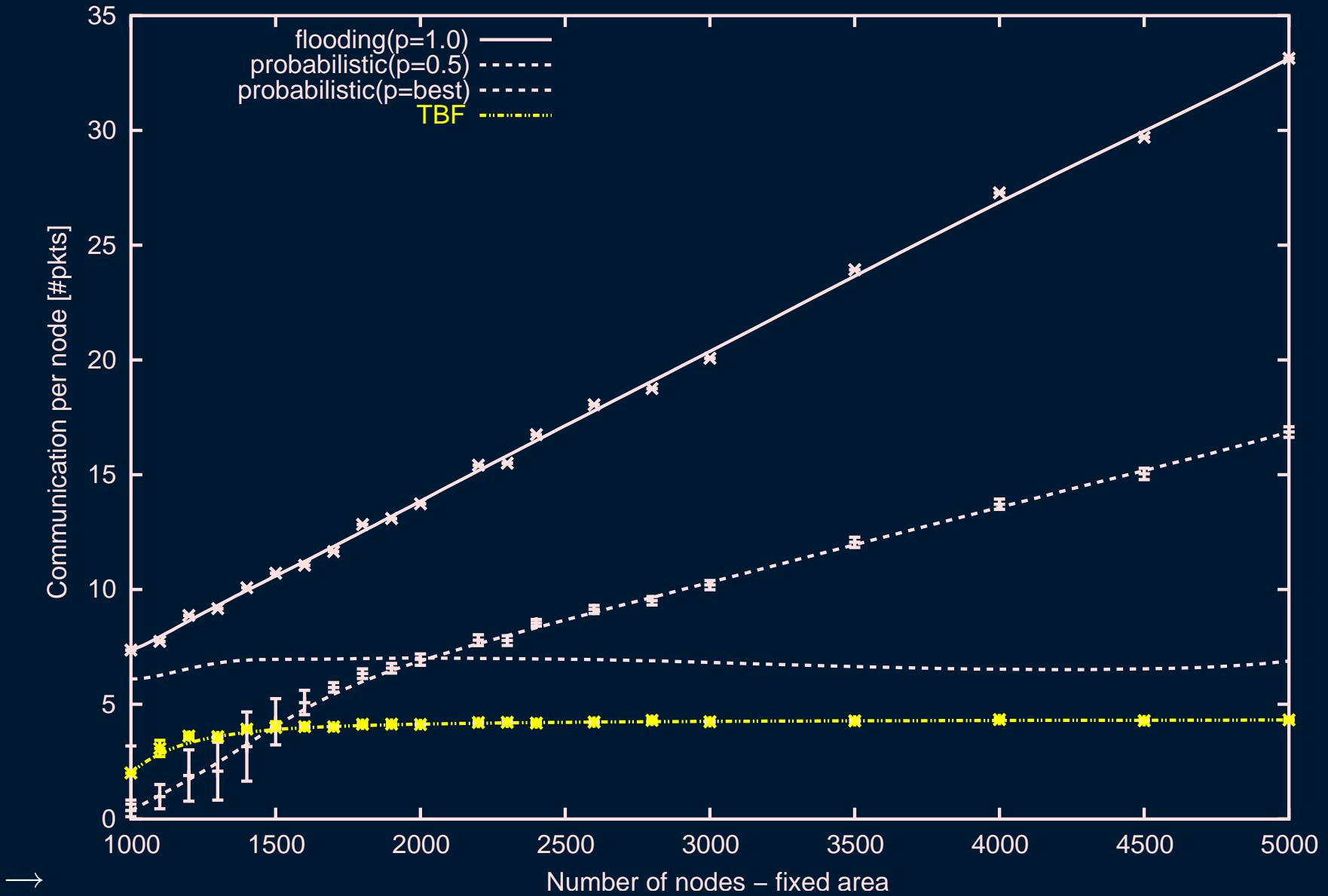
- low impact on path length
- low deviation from ideal trajectory











- <http://www.cs.rutgers.edu/~dnicules/research/>
- “*Ad Hoc Positioning System (APS) using AoA*” - INFOCOM 2003, Elsevier journal of Ad Hoc Networks
- “*Localized Positioning in Ah Hoc Networks*” - SNPA 2003, Elsevier journal of Ad Hoc Networks
- “*Routing on a Curve*” - ACM HOTNETS, 2002
- “*Ad Hoc Positioning System (APS)*” - GLOBECOM 2001, Kluwer journal of Telecommunications Systems